## Pneumatic · 2-Finger Parallel Grippers · Universal Grippers



**Sizes** 50 .. 380



**Weight** 0.125 kg .. 28.0 kg



**Gripping force** 100 N .. 15100 N



Stroke per finger 2 mm .. 45 mm



Force-fit gripping 0.5 kg .. 75.0 kg

### **Application example**



Horizontal turning station with 180° reorientation of the workpiece







Gantry Axis LIRAX-P-SLF-01

### **Universal Gripper**

Universal 2-finger parallel gripper with high gripping force and robust T-slot guidance. Please use the PGN only for replacement orders, for new designs please use the successor model PGN-plus.

### **Area of application**

For universal use in clean to slightly dirty environments. Special solutions are available for use in high temperatures, with dust or corrosion protection. Please ask for more details!

### Your advantages and benefits

#### **High precision T-slot guidance**

For precise handling of a varied range of workpieces

#### **High maximum moments**

Suitable for use with long gripper fingers

## Can be attached from two sides in three screw directions

For universal and flexible gripper mounting

# Air supply via hose-free direct connection or via fittings

For flexible pressure supply in all automated systems

#### **Double-sided air purge connection**

To keep dirt out of the guidance areas



#### General information on the series

#### **Working principle**

Wedge-hook kinematics

#### **Housing material**

Aluminum alloy, hard-anodized

#### Base jaws material

Steel

#### **Actuation**

Pneumatic, via filtered compressed air (10  $\mu$ m): Dry, lubricated or non-lubricated Pressure medium: Requirement on the quality class of compressed air according to DIN ISO 8573-1: Quality class 4

#### Warranty

24 months

#### Scope of delivery

Brackets for proximity switches (only for sizes 64, 80), dowel pins, O-rings for direct connection, guide sleeves, assembly and operating manual with manufacturers declaration

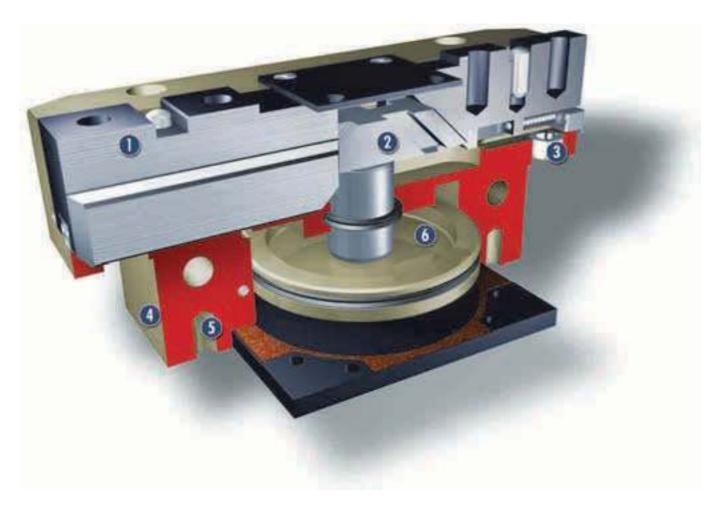
#### Maintenance of gripping force

Possible using variants with mechanical gripping force safety device or pressure maintenance valve SDV-P





### **Sectional diagram**



- Base jaws
  for the adaptation of workpiece-specific
  gripper fingers
- Kinematics
  wedge hook design for high power
  transmission and synchronous gripping
- Sensor systems
  integrated brackets for proximity switches and
  adjustable operating targets
- Weight-reduced thanks to the use of a hardanodized, high-strength aluminum alloy
- Centering and mounting options for universal gripper mounting
- **Drive** pneumatic piston for actuation

### **Functional description**

The round piston is pressed up or down by compressed air. Via its slanted working surfaces, the wedge hook redirects this movement into a lateral, synchronous gripping motion of the two base jaws.

### **Options and special information**

Please use the PGN only for replacement orders, for new designs, please use the successor model PGN-plus.



#### **Accessories**

SCHUNK accessories — the suitable complement for the highest level of functionality, reliability and controlled production of all automation modules.

**Fittings** 



Inductive proximity switches IN



Plastic inserts — Quentes



Sensor cables W/WK/KV/GK



**Gripper pads HKI** 



Sensor distributor V



Pressure maintenance valves SDV-P



Finger blanks



Flexible position sensor



① Please refer to the additional views at the end of each size for the specific size of the equired accessory, availability for the gripper size, the description and the ID No. You can find more detailed information on our range of accessories in the "Accessories" catalog section.

#### General information on the series

#### **Gripping force**

is the arithmetic total of the gripping force applied to each base jaw at distance P (see illustration) measured from the upper edge of the gripper.

#### **Finger length**

is measured from the upper edge of the gripper housing in the direction of the main axis.

#### Repeat accuracy

is defined as the variance of the end position after 100 consecutive strokes.

#### Workpiece weight

The recommended workpiece weight is calculated for force-fit gripping with a friction coefficient of 0.1 and a safety of 2 against slippage of the workpiece on acceleration due to gravity g. Considerably heavier workpiece weights are permitted with form-fit clamping.

#### Closing and opening times

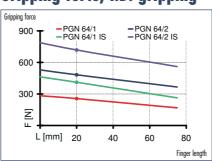
Closing and opening times are the pure movement times of the base jaws or fingers. Valve switching times, hose filling times or PLC reaction times are not included and must be taken into consideration when determining cycle times.



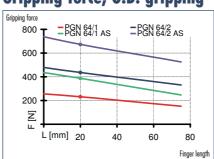
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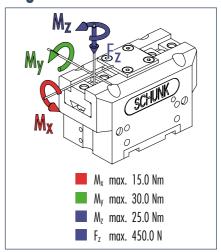
### Gripping force, I.D. gripping



### Gripping force, O.D. gripping



### **Finger load**

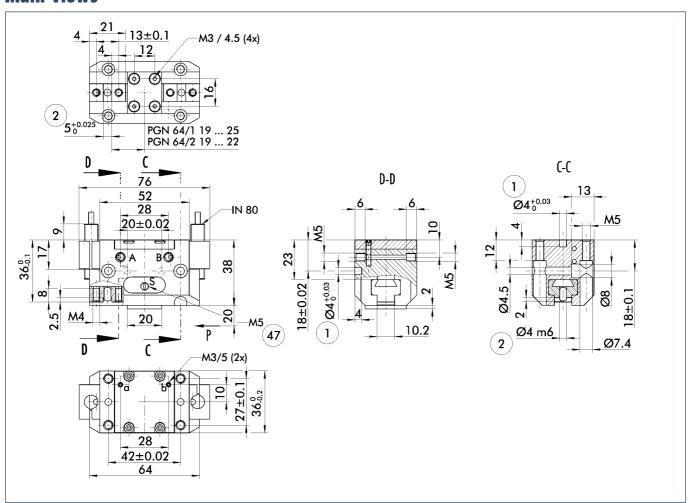


Moments and forces apply per base jaw and may occur simultaneously. M<sub>V</sub> may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. The tool life may be reduced.

### Technical data

Designation		PGN 64-1	PGN 64-2	PGN 64-1 AS	PGN 64-2 AS	PGN 64-1 IS	PGN 64-2 IS
	ID	0370100	0370150	0370400	0370450	0370460	0370470
Stroke per finger	[mm]	6.0	3.0	6.0	3.0	6.0	3.0
Closing force	[N]	220.0	420.0	370.0	740.0		
Opening force	[N]	255.0	480.0			370.0	740.0
Min. gripping force by spring	[N]			70.0	140.0	70.0	140.0
Weight	[kg]	0.27	0.27	0.35	0.35	0.35	0.35
Recommended workpiece weight	[kg]	1.1	2.1	1.1	2.1	1.1	2.1
Air consumption per double stroke	[cm <sup>3</sup> ]	10.0	10.0	10.0	10.0	10.0	10.0
Nominal pressure	[bar]	6.0	6.0	6.0	6.0	6.0	6.0
Minimum pressure	[bar]	2.0	2.0	4.0	4.0	4.0	4.0
Maximum pressure	[bar]	8.0	8.0	6.5	6.5	6.5	6.5
Closing time	[s]	0.02	0.02	0.01	0.01	0.02	0.02
Opening time	[s]	0.02	0.02	0.02	0.02	0.01	0.01
Closing / opening time with spring or	nly [s]			0.05	0.05	0.05	0.05
Max. permitted finger length	[mm]	64.0	64.0	64.0	64.0	64.0	64.0
Max. permitted weight per finger	[kg]	0.3	0.3	0.3	0.3	0.3	0.3
IP class		40	40	40	40	40	40
Min. ambient temperature	[°C]	-10.0	-10.0	-10.0	-10.0	-10.0	-10.0
Max. ambient temperature	[°C]	90.0	90.0	90.0	90.0	90.0	90.0
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01

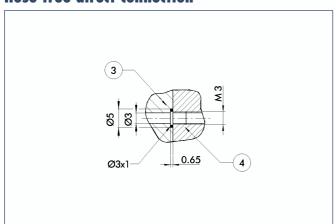
### **Main views**



The illustration shows the gripper in the basic version with closed jaws, without taking into account the measurements of the optional extras described below.

- (i) As an alternative to or in addition to the spring-mounted, mechanical gripping force safety device, the pressure maintenance valve SDV-P can also be used for I.D. or O.D. gripping (see the "Accessories" catalog section).
- A,a Main connection, direct connection Open gripper
- B,b Main connection, direct connection Close gripper
- S,s Air purge connection or vent hole
- 1) Gripper connection
- (2) Finger connection
- (47) On both sides

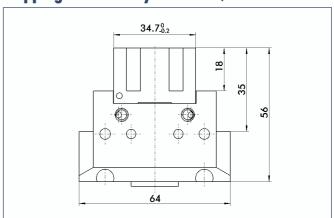
#### **Hose-free direct connection**



- 3 Adapter
- 4 Grippe

The direct connection supplies pressure to the gripper without a failure-prone hose system. Instead, the pressure medium is guided through holes in the mounting plate.

### Gripping force safety device AS/IS

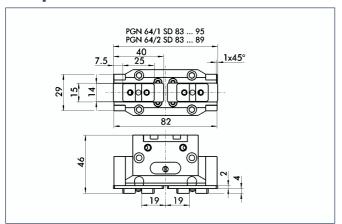


The mechanical gripping force safety device ensures a minimum gripping force, even with a drop in pressure. This works as a closing force for the AS version; for the IS version it works as an opening force. In addition, the gripping force safety device can also be used to increase the grip force or for single actuated gripping.



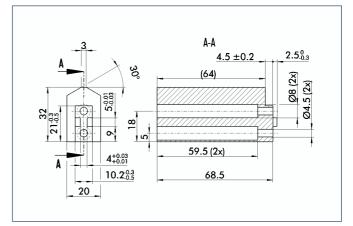
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### **Dust protected version**



The "Dust-proof" option increases the degree of protection against penetrating substances. The screw connection diagram moves by the height of the intermediate jaw. The finger length must still be measured from the upper edge of the gripper housing.

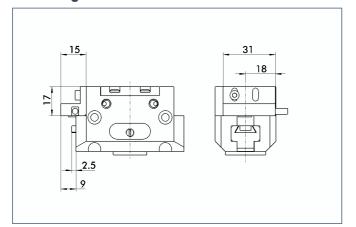
### Finger blanks



Finger blanks for customer-specific reworking, incl. screw connection diagram

Designation	Material	Scope of delivery	ID
ABR 64	Aluminum	1	0300725
SBR 64	16 MnCr 5	1	0300734

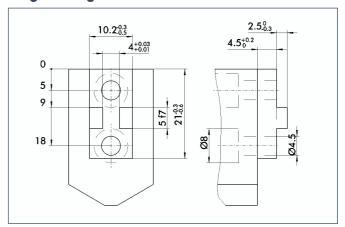
### **Mounting kit for FPS**



The flexible position sensor FPS can distinguish between five freely programmable areas or switching points for the stroke of a gripper and can be used in conjunction with a PC as a measuring system.

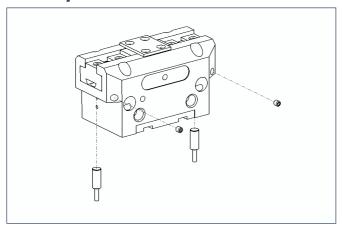
Designation	ID	
AS-PGN 64-100/ HGN 80-100	0301710	

### Finger design



Suggestion for connection dimensions — Gripper fingers

## Sensor systems

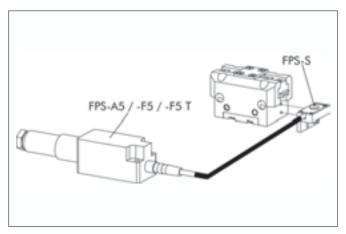


End position monitoring:

Inductive proximity switches, for direct mounting

Designation	ID	Recommended product
IN 80/S-M12	0301578	
IN 80/S-M8	0301478	•
IN-B 80/S-M8	0301477	
INK 80/S	0301550	

(1) Two sensors (NO contacts/S) are required per gripper as well as an optional extension cable.



Measuring system:

Position monitoring FPS

Designation	ID	
AS-PGN 64-100/ HGN 80-100	0301710	
FPS-A5	0301802	
FPS-F5	0301805	
FPS-F5 T	0301807	
FPS-S 13	0301705	

When using an FPS system, an FPS sensor (FPS-S) and an electronic processor (FPS-F5/F5 T or A5) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are available as optional extras in the "Accessories" catalog section.

Extension cables for proximity switches/magnetic switches

Designation	עו	
GK 3-M8	0301622	
KV 10-M12	0301596	
KV 10-M8	0301496	
KV 20-M12	0301597	
KV 20-M8	0301497	
KV 3-M12	0301595	
KV 3-M8	0301495	
W 3-M12	0301503	
W 5-M12	0301507	
WK 3-M8	0301594	
WK 5-M8	0301502	

(i) For the sensor cables, observe the minimum permitted bending radii. Generally, these are 35 mm.

